

A New Approach to Solve Angular Dispersion of Discrete Ray Launching for Urban Scenarios

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INTRODUCTION

Ray launching suffers from angular dispersion. Distant pixels are often missed when rays disperse. A fast discrete ray launching model is developed to validate the use of this approach. It has enabled the practical use of this model in other scenarios (indoor, indoor-to-outdoor)

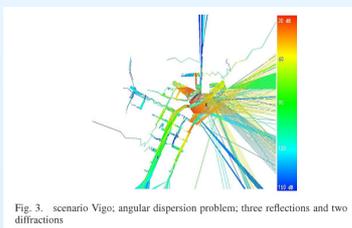
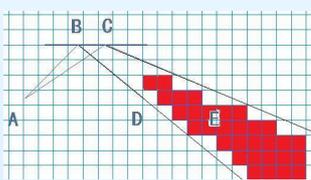


Fig. 3. scenario Vigo; angular dispersion problem; three reflections and two diffractions

OBJECTIVES

- To solve angular dispersion of discrete ray launching
- To improve the accuracy of ray launching propagation models
- To speed up ray launching
- To extend the principle to indoor, indoor-to-outdoor propagation prediction

APPLICATIONS

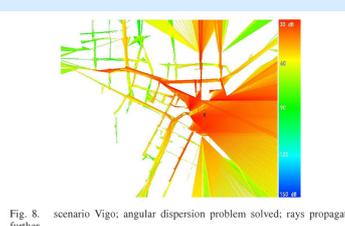
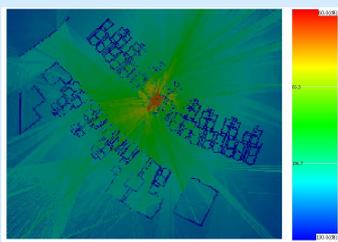
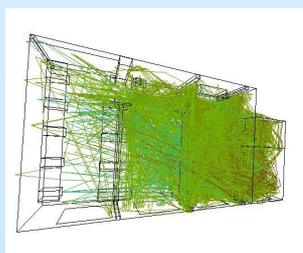


Fig. 8. scenario Vigo; angular dispersion problem solved; rays propagate further

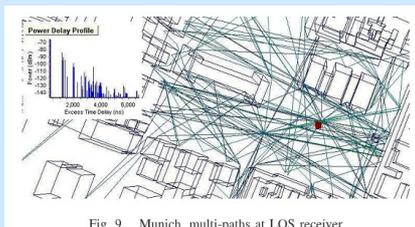
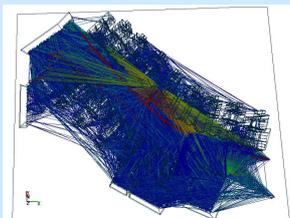
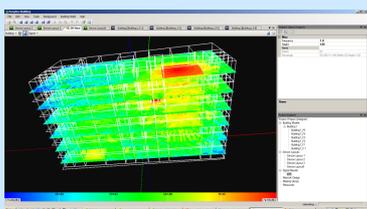
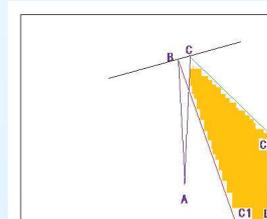


Fig. 9. Munich, multi-paths at LOS receiver

SOLUTIONS

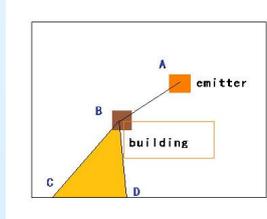
- Fill the gap between reflection rays
- Fill the gap between diffraction rays
- Avoid double marking the same pixels



Algorithm 1 avoid pixels missing (reflection)

```

 $v_1$  ← Reflection Ray 1 (C-A)
 $v_2$  ← Reflection Ray 2 (C-B)
 $c_1$  ← Boundary Cube that  $v_1$  hits
 $c_2$  ← Boundary Cube that  $v_2$  hits
for all  $C \in$  Cubes between  $c_1$  and  $c_2$  do
    Launch Reflection Rays from A(or B) to C
end for
    
```



Algorithm 2 avoid double marking

```

 $M_r$  ← 3D counter matrix for reflection
 $M_d$  ← 3D counter matrix for diffraction
 $C_r$  ← Initial reflection counter
 $C_d$  ← Initial diffraction counter
Inc( $C_r$ ) if reflection shadow area is being handled.
Inc( $C_d$ ) if diffraction shadow area is being handled.
if  $M_r[\text{current cube}] \neq C_r$  then
    handle_reflection(current cube)
     $M_r[\text{current cube}] \leftarrow C_r$ 
    collect current cube for next reflection
end if
if  $M_d[\text{current cube}] \neq C_d$  then
    handle_diffraction(current cube)
     $M_d[\text{current cube}] \leftarrow C_d$ 
    collect current cube for next diffraction
end if
    
```

RESULTS

- A fast and accurate discrete ray launching model for outdoor, indoor and indoor-to-outdoor has been developed.
- Significant speedup through parallelism via POP-C++

TABLE I
NETWORK CONFIGURATIONS FOR BOTH RUNS

Area	8.1 km ² (2.4km X 3.4km X 100m)
Buildings	308
Antenna Type	Omnis
Emitter Frequency	GSM 947MHz
Resolution	5 X 5 X 5
Maximum Reflection	3
Maximum Horizontal Diffraction	7
Maximum Vertical Diffraction	Unlimited *
Maximum Transmission	Unlimited *

* until signal strength is under threshold

TABLE II
COMPARISONS FOR BOTH RUNS

	With	Without
Total Reflections	121, 170	89, 902
Total Diffractions	157, 201	101, 356
Total Multi-paths	122, 722	93, 521
Avg STD for 3 routes	7.11	7.81
Avg RMSE for 3 routes	7.02	7.69
Avg running time (s)	49	22

References

- [1] Z. Lai, N. Bessis, G. de la Roche, H. Song, J. Zhang and G. Clapworthy, An intelligent ray launching for urban coverage prediction, 3rd European Conference on Antennas and Propagation EUCAP 2009, Berlin, Germany, 23-27 March 2009, pp. 2867-2871.
- [2] G. de la Roche, J. Gorce and J. Zhang, Optimized implementation of the 3-D MR-FDPF method for Indoor radio propagation predictions, 3rd European Conference on Antennas and Propagation EUCAP 2009, Berlin, Germany, 23-27 March 2009, pp. 2241-2245.
- [3] Z. Lai, N. Bessis, P. Kunoen, G. de la Roche, J. Zhang and G. Clapworthy, A performance evaluation of a grid-enabled object-oriented parallel outdoor ray launching for wireless network coverage prediction, The Fifth International Conference On Wireless and Mobile Communications ICWMC 2009, Cannes/La Bocca, France, 23-28 August 2009, pp. 38-43